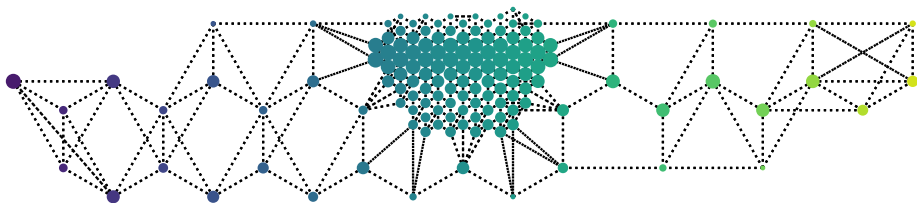


Direction and energy reconstruction with uncertainty quantification for GRAND using graph neural network

Warsaw collaboration meeting

Arsène Ferrière



Advisors : Aurélien Benoit-Lévy, Olivier Martineau

Why Machine Learning ?

- ▶ Work directly from data-like inputs
- ▶ Fast and reliable data analysis : Direction and Energy reconstruction
- ▶ Background event rejection

But, need for labeled data \implies Training on simulations = complications :

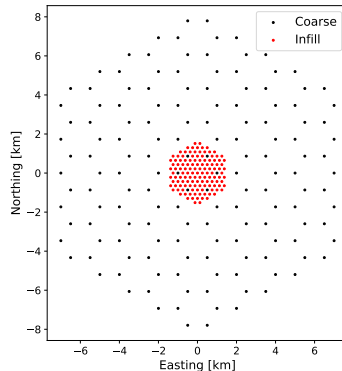
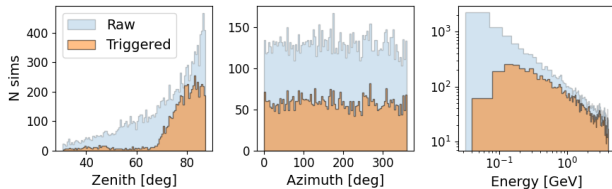
- ▶ How to make sure the reconstruction will work on real data ?
- ▶ How to properly simulate the measurement noise ?
- ▶ What level of confidence to give to the predictions ?

Developing reliable AI with uncertainty quantification.

Simulation set

Antenna layout

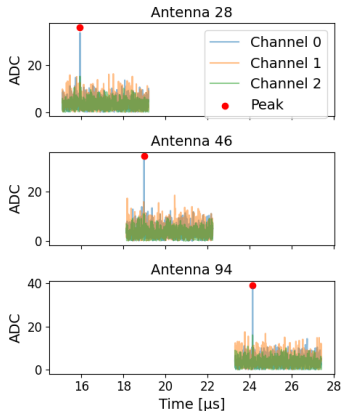
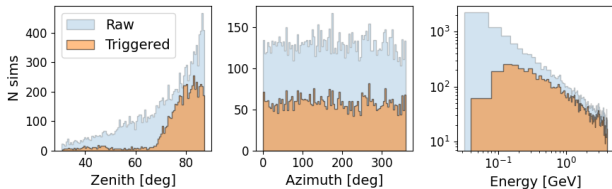
1. DC2 ADC simulations
2. Low galactic noise + 5ns jitter
3. Extract time and amplitude of maximum
4. Trigger condition : $\text{Signal} \geq 30\text{ADC}$ (5σ)
for more than 5 antennas.



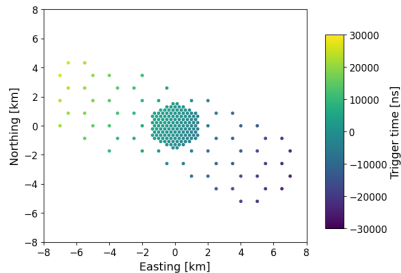
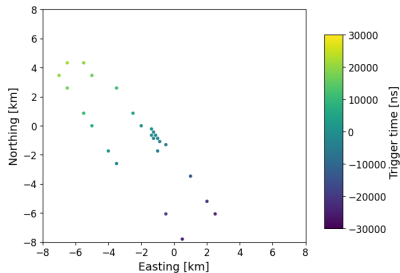
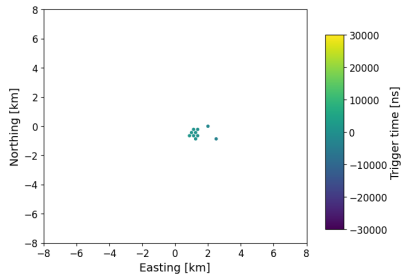
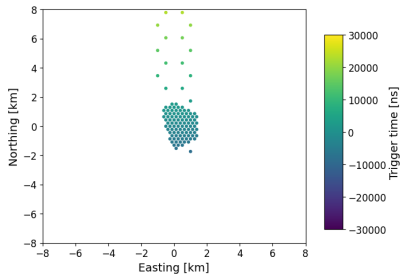
Simulation set

Trace example

1. DC2 ADC simulations
2. Low galactic noise + 5ns jitter
3. Extract time and amplitude of maximum
4. Trigger condition : $\text{Signal} \geq 30\text{ADC}$ (5σ) for more than 5 antennas.



Event examples



Wide variety of events:
Varying footprint size,
shape, antenna multiplicity
**Constraint on the
possible NN architecture**

GNN explanation

Key Steps in a GNN Layer: [Scarselli et al.]

- ▶ **Message Passing:** Each node aggregates information from its neighbors.
- ▶ **Aggregation:** Information is combined using a function (e.g., sum, mean, max).
- ▶ **Update:** Node embeddings are updated using a neural network (e.g., MLP).

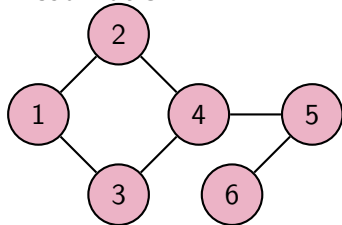
Mathematical Formulation:

$$h_i^{(l+1)} = \sigma(\text{AGG}_{j \in \mathcal{N}(i)}(f_{\omega_l}[h_i^{(l)}, h_j^{(l)}])),$$

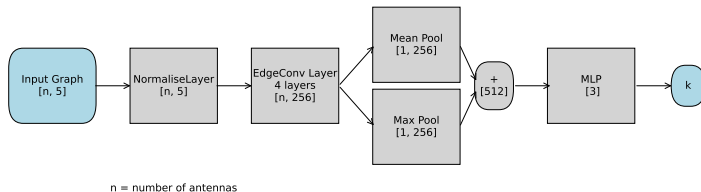
where:

- ▶ $h_i^{(l)}$: Node embedding at layer l .
- ▶ $\mathcal{N}(i)$: Neighbors of node i .
- ▶ f_{ω_l} : Is a function with trainable parameters (MLP).
- ▶ σ : Non-linear activation (e.g., ReLU).

Visualization:



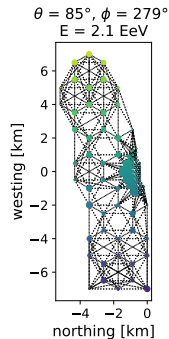
Architecture of Graph Neural Networks



Architecture of graph neural networks:
780k parameters (can be reduced to 60k)

EdgeConv Layer [Abbasi et al.]:

$$x_{\mu}^{k+1} = \sigma \left(\frac{1}{|N_{\mu}|} \sum_{\nu \in N_{\mu}} f_{\theta}(x_{\mu}^k, x_{\nu}^k) \right)$$



8 nearest neighbours

Training procedure

Direction reconstruction

Reconstructing θ, ϕ : No direct reconstruction.

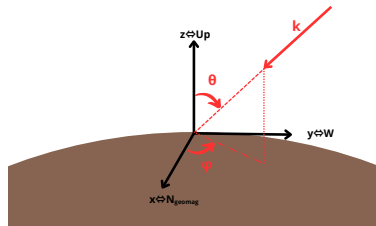
Better in cartesian coordinates: \mathbf{k}

- ▶ Loss function $L(\omega) = \mathbb{E}[||\mathbf{k}_{\text{pred}} - \mathbf{k}_{\text{sim}}||^2]$
- ▶ 5 input features: 3 antenna coordinates, arrival time, signal amplitude (normalised)
- ▶ **Training set**: 4937 events, **Validation set**: 928 events
- ▶ 10 models or more trained with different initialization/Train dataset order

Ensemble methods:

With the N models, 1 "meta model".

$$\mathbf{k}_{\text{pred}} = \frac{1}{N} \sum_{i=1}^N \mathbf{k}_{\text{pred},i}$$

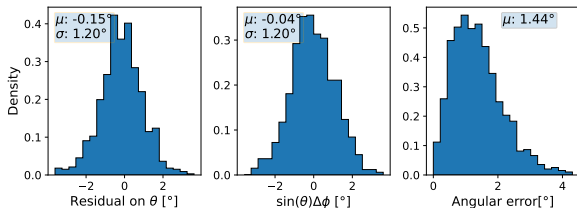


Parameters convention

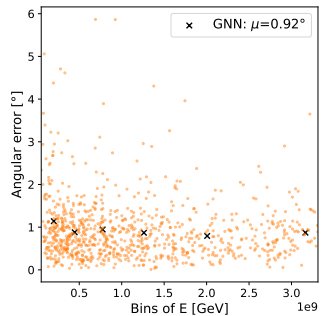
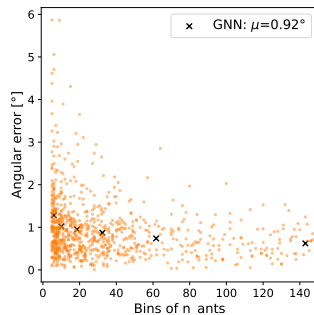
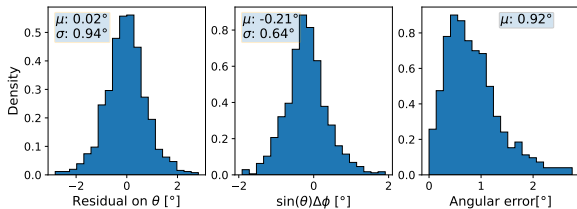
Performance

Direction reconstruction

Single model predictions

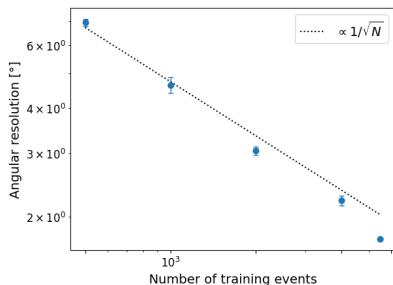


Ensemble method



Training set size

Influence of training set size



Evolution of the error when increasing the training set size.

Extrapolation is no reason yet :

Suggests that larger training set \Rightarrow Better performances.

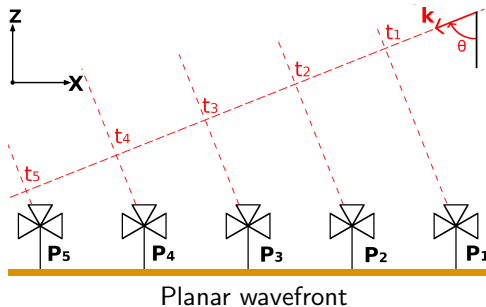
To avoid using more simulations : Feed physical knowledge to network.

Physical knowledge

What is PWF ?

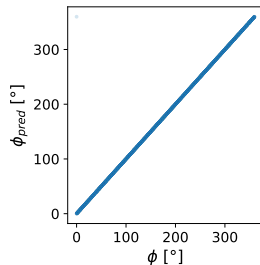
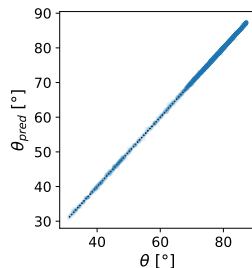
Assume the wavefront is planar:

Linear relation between timings \mathbf{T} , position \mathbf{P} and propagation vector \mathbf{k} :



Solution :

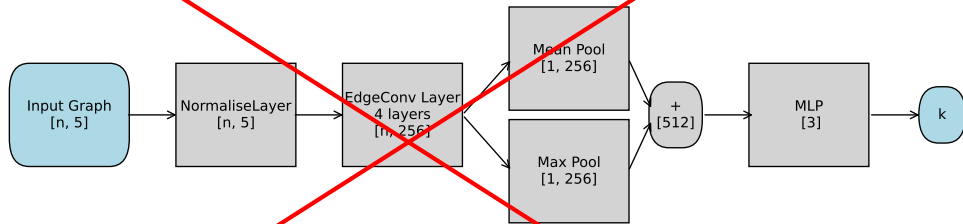
$$\mathbf{k} = \operatorname{argmin}(\mathbf{T} - \mathbf{P}\mathbf{k})^T(\mathbf{T} - \mathbf{P}\mathbf{k}) \text{ s.t. } \|\mathbf{k}\| = c$$



[Github repository](#)

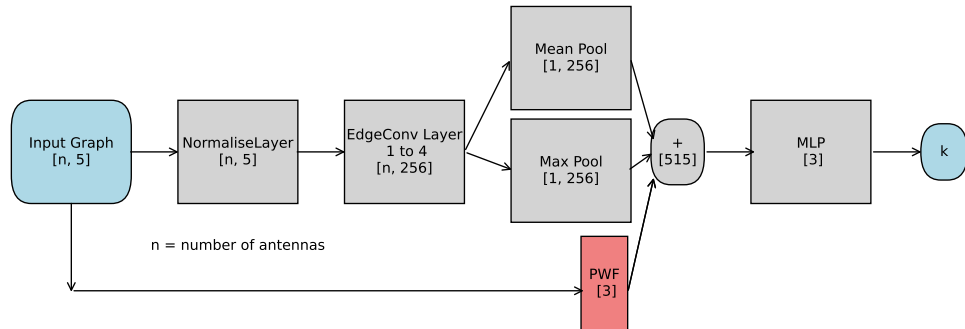
[Ferriere et al. 2025]_{11/25}

New Architecture of Graph Neural Networks : pGNN



n = number of antennas

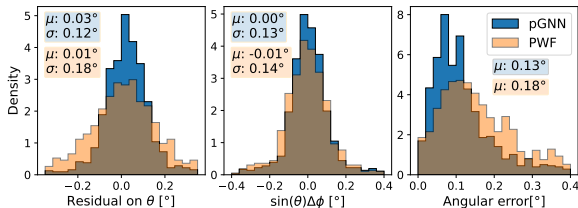
New Architecture of Graph Neural Networks : pGNN



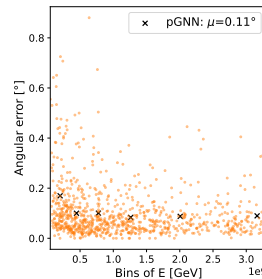
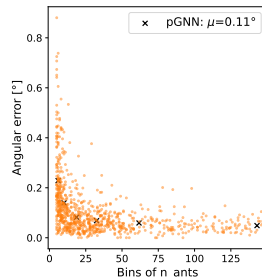
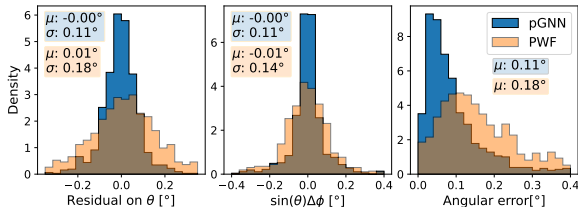
Performance

Direction reconstruction

Single model predictions



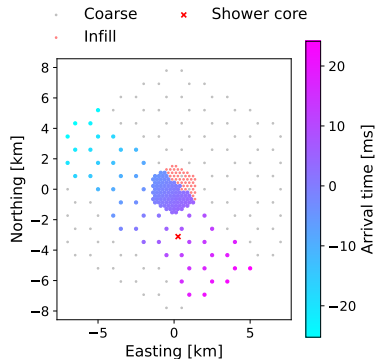
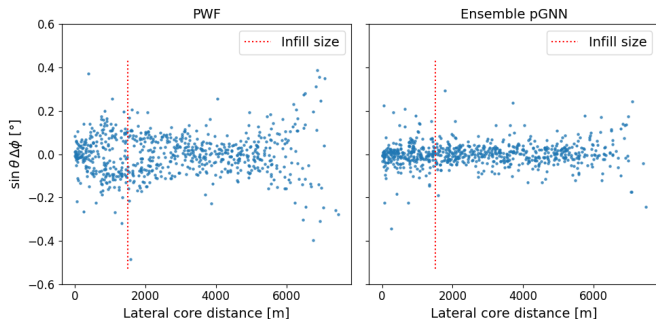
Ensemble method



$\times 10$ improvement compared to raw GNN

Correction of the PWF bias

PWF is known to be biased when asymmetries in the antenna footprint.



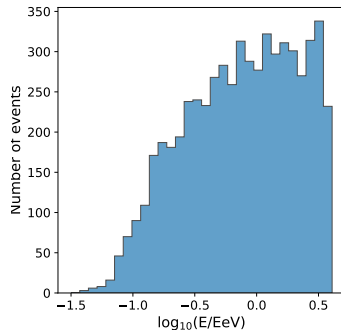
[Ferrière et al. in prep]

Training procedure and performances

Energy reconstruction - *Work in progress*

Reconstructing E ? No : Uneven distribution. Better $\log E$.

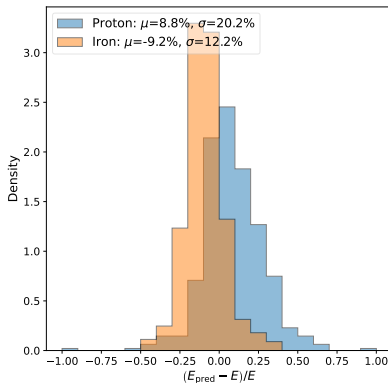
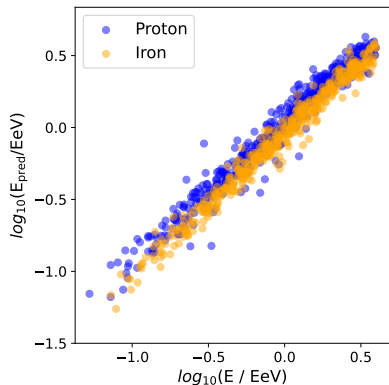
- ▶ Loss function $L(\omega) = \mathbb{E}[\log \left(\frac{E_{pred}}{E_{target}} \right)^2]$
- ▶ 5 input features: 3 antenna coordinates, arrival time, signal amplitude (normalised)
- ▶ **Training set**: 4937 events, **Validation set**: 928 events
- ▶ 10 models or more trained with different initialization/Train dataset order
- ▶ Secondary input : **PWF** + polynomial fit of energy from (average amplitude, maximum amplitude, number of antennas, PWF zenith angle)



$\log E$ distribution

Energy resolution

Energy reconstruction - *Work in progress*



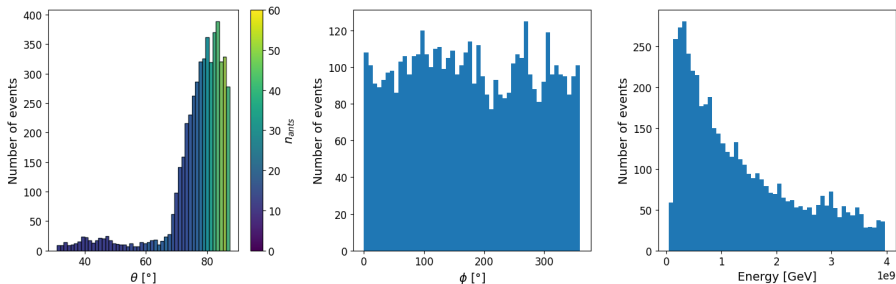
Total energy resolution : 19.5%

For primary energy!

On more realistic simulation

Direction reconstruction

On sims with the new RF chain and effective length: $\text{mult} \geq 5$, trigger at 85 ADC:

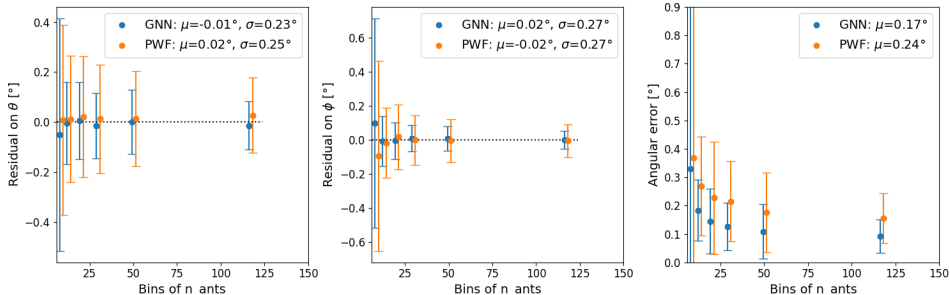


Distribution of triggered events

On more realistic simulation

Direction reconstruction

Difficult training as much lower SNR \implies less dus per event

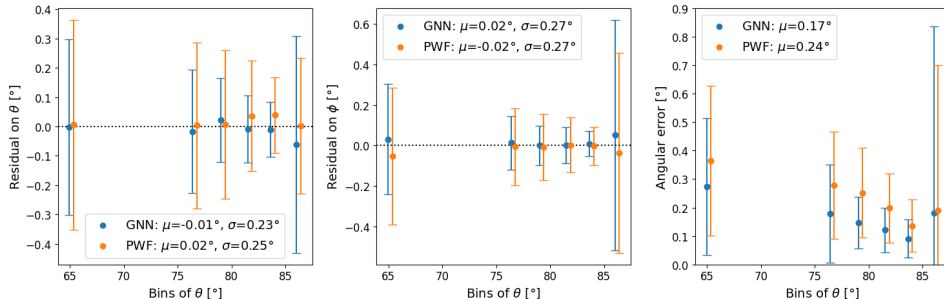


Performance vs antenna multiplicity (mult ≥ 6 : 91% of events)

On more realistic simulation

Direction reconstruction

Difficult training as much lower SNR \Rightarrow less μ per event

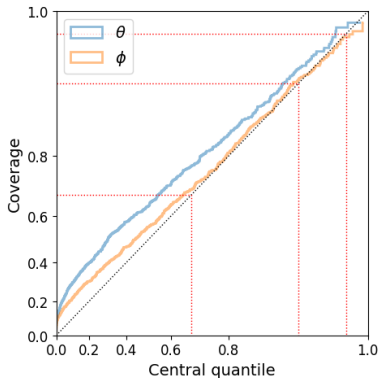


Performance vs incoming angles (mult ≥ 6 : 91% of events)

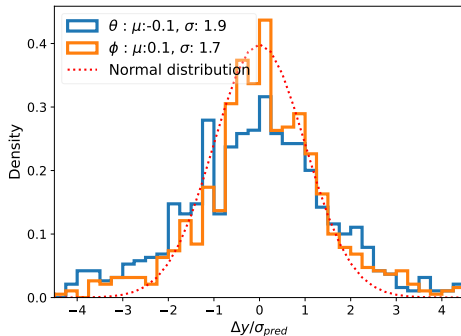
Uncertainty estimation

Direction reconstruction

Under Gaussian assumption : $\theta \sim \mathcal{N}(\mu_\theta, \sigma_\theta^2)$ and $\phi \sim \mathcal{N}(\mu_\phi, \sigma_\phi^2)$. With μ_θ the mean of our 30 predictions of θ and σ_θ their std's.



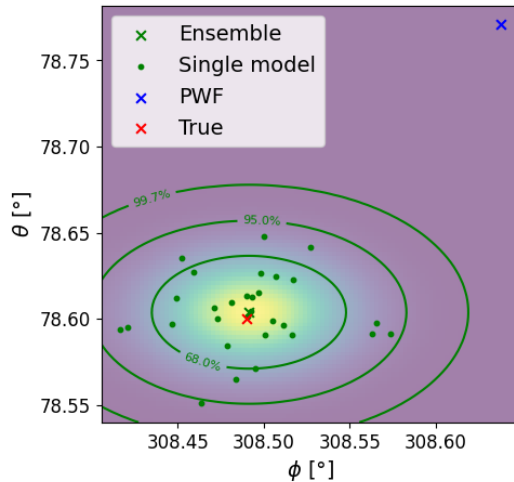
PP plot for our uncertainty estimator. We slightly overestimate our uncertainties for θ



Distribution of normalized residuals

Uncertainty estimation

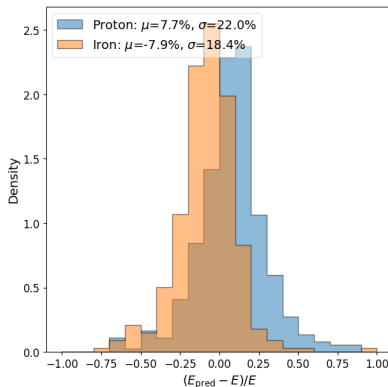
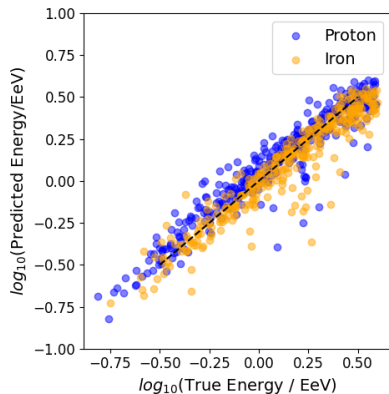
Direction reconstruction



Example of reconstruction

Energy resolution

Energy reconstruction - *Work in progress*



Total energy resolution : 21.7%
For primary energy!

Left to do

Direction reconstruction

1. Improve energy reconstruction on the new set of simulation
2. More robust testing on triggering effects/smearing effects
3. Add features (spectral slope, polarization)



Conclusion

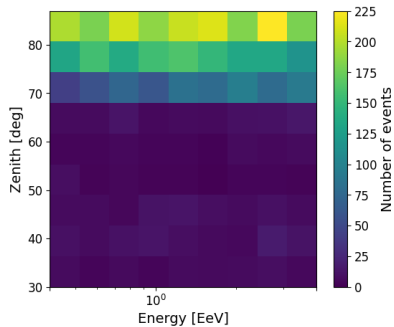
Results - Direction on data-like simulation

- ▶ With GNN and ensemble methods, high direction reconstruction precision : 0.17° precision for $n_{ants} \geq 6$.
- ▶ Slightly overconfident uncertainty estimation.

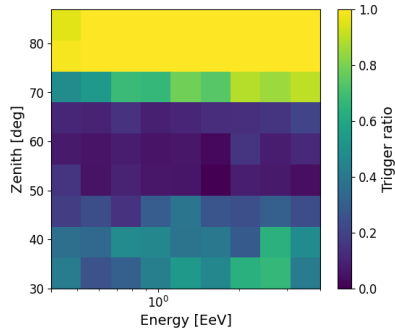
Results - Energy on simulation

- ▶ Energy resolution : 21.6%
- ▶ Uncertainty estimation not yet calibrated.

Backup slides : joint trigger distribution



Joint trigger distribution

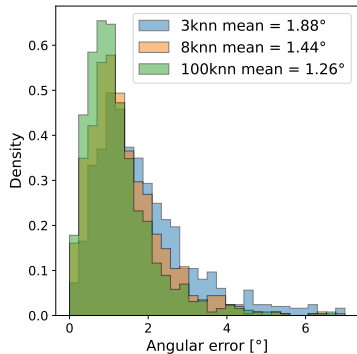


joint trigger ratio

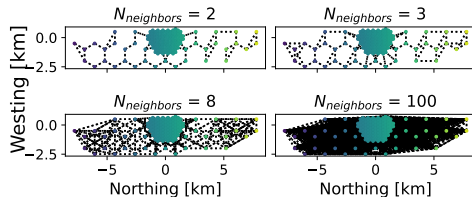
Training set size and graph structure

Direction reconstruction

Influence of graph structure



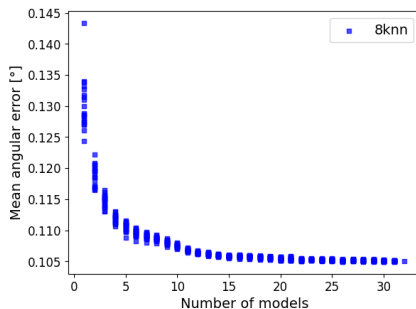
Degradation of performance when lowering
number of neighbours



- ▶ if $N_{neighbors} = 3$: graph depth = 8.18
- ▶ if $N_{neighbors} = 8$: graph depth = 3.9
- ▶ if $N_{neighbors} = 100$: graph depth = 1.14

Ensemble size

We have a net improvement of the performances of the direction reconstruction with the same training size.



Evolution of the precision with the number of models